# Local subcell monolithic DG/FV scheme

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- DG as a subcell FV
- Monolithic subcell DG/FV scheme
- Entropy stabilities
- 5 Maximum principles
  - 6 Conclusion

# Scalar Conservation Law (SCL)

- $\partial_t u(\mathbf{x}, t) + \nabla_x \cdot \mathbf{F}(u(\mathbf{x}, t)) = 0, \qquad (\mathbf{x}, t) \in \mathbb{R}^d \times [0, T]$
- $u(\mathbf{x}, 0) = u_0(\mathbf{x}),$

$$\mathbf{X} \in \mathbb{R}^d$$

# **Fundamental difficulty**

- Even considering smooth flux function  $F(\cdot)$  and initial datum  $u_0(\cdot)$  ( $C^{\infty}$  for instance), solution may become discontinuous in finite time
- Standard example: Burgers equation

$$\begin{cases} \partial_t u + \partial_x \left(\frac{1}{2}u^2\right) = 0, & (x,t) \in [0,1] \times \mathbb{R}^+, \\ u(x,0) = \sin(2\pi x), & x \in [0,1]. \end{cases}$$

# Strong solution

• Local in time existence and uniqueness of a solution  $u \in C^1(\mathbb{R}^d \times [0, t_c[)$ 

#### Conservation laws

# Formation of a discontinuity in finite time

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# Weak solution

• 
$$\int \int_{\mathbb{R}^d \times \mathbb{R}^+} \left( u \, \partial_t \psi + \boldsymbol{F}(u) \cdot \nabla_x \psi \right) \, \mathrm{d}\boldsymbol{x} \, \mathrm{d}t - \int_{\mathbb{R}^d} u_0(\boldsymbol{x}) \, \psi(\boldsymbol{x}, 0) \, \mathrm{d}\boldsymbol{x} = 0$$

• Non-uniqueness of a weak solution  $u \in L^{\infty}_{loc}(\mathbb{R}^d \times \mathbb{R}^+)$ 

# Entropy definition

- Let  $u \in C^1(\mathbb{R}^d \times [0, t_c[)])$  be a strong solution
- $\eta$  a strictly convex function is an entropy if  $\exists \phi$  s.t.

 $\partial_t \eta(u) + \nabla_x \cdot \phi(u) = 0$ 

# Unique entropic weak solution

 $\forall \psi \in \mathcal{C}_0^1(\mathbb{R}^d \times \mathbb{R}^+)$ 

 $\forall \psi \in \mathcal{C}_0^1(\mathbb{R}^d \times \mathbb{R}^+)$ 

- Let  $u \in L^{\infty}_{loc}(\mathbb{R}^d \times \mathbb{R}^+)$  be a weak solution
- *u* is the unique entropic weak solution if it satisfies, for any pair  $(\eta, \phi)$

$$\int \int_{\mathbb{R}^d \times \mathbb{R}^d} \left( \eta(u) \, \partial_t \psi + \phi(u) \, \cdot \, \nabla_x \psi \right) \, \mathrm{d} \boldsymbol{x} \, \mathrm{d} t - \int_{\mathbb{R}^d} \eta \left( u_0(\boldsymbol{x}) \right) \psi(\boldsymbol{x}, 0) \, \mathrm{d} \boldsymbol{x} \ge 0$$

#### Conservation laws

# Formation of a discontinuity in finite time

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# Challenges of numerical discretization

- The weak solution we wish to approach may present areas of great regularity as well as discontinuities of great intensity
- → Smooth areas: high accuracy
- ----> Discontinuities: strong robustness and stability
- ---> Everywhere: additional mathematical or physical constraints
  - ↔ Maximum principle or positivity
  - $\hookrightarrow$  Entropy inequalities

 $\hookrightarrow \ldots$ 

# Numerical schemes and discontinuous approximated solution

Finite Volume
(Weighted) Essentially Non-Oscillatory
Discontinuous Galerkin

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F۷

DG

(W)-ENO

#### Discontinuous Galerkin scheme

- Introduced by Reed and Hill in 1973 in the frame of the neutron transport
- Major development and improvements by B. Cockburn and C.-W. Shu

#### Procedure

- Local variational formulation
- Piecewise polynomial approximation of the solution in the cells
- Choice of the numerical fluxes
- Time integration

#### Advantages

- Natural extension of Finite Volume method
- Excellent analytical properties (L<sub>2</sub> stability, hp-adaptivity, ...)
- Extremely high accuracy (superconvergent for scalar conservation laws)
- Compact stencil (involve only face neighboring cells)

#### Scalar conservation law

•  $\partial_t u(\mathbf{x}, t) + \nabla_x \cdot \mathbf{F}(u(\mathbf{x}, t)) = 0, \quad (\mathbf{x}, t) \in \omega \times [0, T]$ 

• 
$$u(\mathbf{x}, \mathbf{0}) = u_{\mathbf{0}}(\mathbf{x}),$$
  $\mathbf{x} \in \omega$ 

# $(k+1)^{\text{th}}$ order semi-discretization

- $\{\omega_c\}_c$  a partition of  $\omega$ , such that  $\omega = \bigcup_c \omega_c$
- $u_h(\mathbf{x}, t)$  the numerical solution, such that  $u_{h|\omega_c} = u_h^c \in \mathbb{P}^k(\omega_c)$

$$u_h^c(\mathbf{x},t) = \sum_{m=1}^{N_k} u_m^c(t) \, \sigma_m^c(\mathbf{x})$$

• 
$$\{\sigma_m^c\}_{m=1,...,N_k}$$
 a basis of  $\mathbb{P}^k(\omega_c)$ , with  $N_k = \frac{(k+1)(k+2)}{2}$  in 2D.

# Local variational formulation on $\omega_c$

• 
$$\int_{\omega_c} \frac{\partial u_h^c}{\partial t} \psi \, \mathrm{d} V = \oint_{\omega_c} \mathbf{F}(u_h^c) \cdot \nabla_x \psi \, \mathrm{d} V - \oint_{\partial \omega_c} \psi \, \mathcal{F}_n \, \mathrm{d} S,$$

$$\forall \psi \in \mathbb{P}^{\kappa}(\omega_{c})$$

#### numerical flux

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•  $\mathcal{F}_n = \mathcal{F}(u_b^c, u_b^v, \mathbf{n})$ 

# Numerical example: solid body rotation



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#### Rotation of composite signal



# Rotation of composite signal



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# Spurious oscillations, aliasing and non-entropic behavior



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#### Gibbs phenomenon and non-admissible solution

- High-order schemes leads to spurious oscillations near discontinuities
- Non-admissible solution potentially leading to a crash
- Vast literature of how prevent this phenomenon to happen:

⇒ a priori and a posteriori limitations

# A priori limitation

- Artificial viscosity
- Slope/moment/hierarchical limiter
- ENO/WENO limiter
- Flux limiter and FCT schemes
- Monolithic HO/LO schemes

# A posteriori limitation

- MOOD ("Multi-dimensional Optimal Order Detection")
- A posteriori subcell correction

#### Admissible numerical solution

- Maximum principle / positivity preserving
- Limit the apparition of spurious oscillations
- Ensure a correct entropic behavior

Preserving high-accuracy and subcell resolution

Reduce the characteristic length of action

Methodology

Blend, at the subcell scale, high-order DG and 1st-order FV

- **F.V.**, A Posteriori Correction of High-Order DG Scheme through Subcell Finite Volume Formulation and Flux Reconstruction. JCP, 2018.
- **F.V.**, Local subcell monolithic DG/FV convex property preserving scheme on unstructured grids and entropy consideration. JCP, 2024.

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# DG schemes through residuals

• 
$$(U_c)_m = u_m^c$$
 Solution moments  
•  $(M_c)_{mp} = \int_{\omega_c} \sigma_m \sigma_p \, dV$  Mass matrix  
•  $(\Phi_c)_m = \oint_{\omega_c} \mathbf{F}(u_h^c) \cdot \nabla_x \sigma_m \, dV - \oint_{\partial \omega_c} \sigma_m \, \mathcal{F}_n \, dS$  DG residuals

# Subdivision and definition

•  $\omega_c$  is subdivided into  $N_s$  subcells  $S_m^c$ 

• Let us define 
$$\overline{\psi}_m^c = \frac{1}{|S_m^c|} \int_{S_m^c} \psi \, \mathrm{d}V$$
 the subcell mean value

# Submean values

• 
$$\overline{u}_{m}^{c} = \frac{1}{|S_{m}^{c}|} \sum_{q=1}^{N_{k}} u_{q}^{c} \int_{S_{m}^{c}} \sigma_{q} \, dV \implies \overline{U_{c} = P_{c} U_{c}}$$
  
•  $(\overline{U}_{c})_{m} = \overline{u}_{m}^{c}$  Submean values  
•  $(P_{c})_{mp} = \frac{1}{|S_{m}^{c}|} \int_{S_{m}^{c}} \sigma_{p} \, dV$  Projection matrix  
 $\Rightarrow \qquad \boxed{\frac{d\overline{U}_{c}}{dt} = P_{c} M_{c}^{-1} \Phi_{c}}$   
Admissibility of the cell sub-partition into subcells  
•  $P_{c}^{t} P_{c}$  has to be non-singular  
 $\Rightarrow \qquad \boxed{U_{c} = (P_{c}^{t} P_{c})^{-1} P_{c}^{t} \overline{U}_{c}}$  Least square procedure  
• If  $N_{r} = N_{r}$   $\overline{U}_{c} = P_{c} H_{c} \Leftrightarrow H_{c} = P_{c}^{-1} \overline{H}_{c}$ 

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# Subcell Finite Volume: reconstructed fluxes

Let us introduce the reconstructed fluxes

$$\frac{\mathrm{d}\,\overline{u}_m^c}{\mathrm{d}t} = -\frac{1}{|S_m^c|} \sum_{S_p^v \in \mathcal{V}_m^c} I_{mp}\,\widehat{F_{pm}}$$

- $\mathcal{V}_m^c$  the set of face neighboring subcells of  $\mathcal{S}_m^c$
- We impose that on the boundary of cell  $\omega_c$ , so for  $S_p^v \notin \omega_c$

$$I_{mp} \, \widehat{F_{pm}} = \oint_{f_{mp}^c} \mathcal{F}_n \, \mathrm{d}\boldsymbol{S} \equiv \oint_{f_{mp}^c} \mathcal{F}\left(\boldsymbol{u}_h^c, \, \boldsymbol{u}_h^v, \, \boldsymbol{n}_{mp}^c\right) \, \mathrm{d}\boldsymbol{S}$$

- $\widetilde{\mathcal{V}_m^c}$  the set of face neighboring subcells of  $S_m^c$  belonging to  $\omega_c$
- Let  $A_c$  be the adjacency matrix such that

$$(\mathbf{A}_{c})_{mp} = \begin{cases} 1 & \text{if } S_{p}^{v} \in \widecheck{\mathcal{V}_{m}^{c}} \text{ with } m < p, \\ -1 & \text{if } S_{p}^{v} \in \widecheck{\mathcal{V}_{m}^{c}} \text{ with } m > p, \\ 0 & \text{if } S_{p}^{v} \notin \widecheck{\mathcal{V}_{m}^{c}}. \end{cases}$$

## Subcell Finite Volume: reconstructed fluxes

• Let us introduce  $D_c = \text{diag}\left(|S_1^c|, \dots, |S_{N_k}^c|\right)$  and  $(B_c)_m = \int_{\partial S_m^c \cap \partial \omega_c} \mathcal{F}_n \, \mathrm{d}S$ 

• Let  $\widehat{F_c}$  be the vector containing all the interior faces reconstructed fluxes

$$-A_c \, \widehat{\mathsf{F}_c} = D_c \, P_c \, M_c^{-1} \, \Phi_c + \mathsf{B}_c$$

## Graph Laplacian technique

•  $A_c \in \mathcal{M}_{N_s \times N_f^c}$  with  $N_f^c$  the number of interior faces •  $(L_c)_{mp} := (A_c A_c^t)_{mp} = \begin{cases} |\widetilde{\mathcal{V}_m^c}| & \text{if } m = p, \\ -1 & \text{if } S_p^v \in \widetilde{\mathcal{V}_m^c}, \\ 0 & \text{otherwise.} \end{cases}$ •  $L_c \mathbf{1} = \mathbf{0}$  where  $\mathbf{1} = (1, \dots, 1)^t \in \mathbb{R}^{N_s}$ •  $\Pi = \frac{1}{N_s} (\mathbf{1} \otimes \mathbf{1}) \in \mathcal{M}_{N_s}$ 

# Graph Laplacian technique

• Let  $\mathcal{L}_c^{-1}$  be the pseudo-inverse of  $L_c$  such that

$$\mathcal{L}_{c}^{-1} = (\mathcal{L}_{c} + \lambda \Pi)^{-1} - \frac{1}{\lambda} \Pi \qquad \forall \lambda \neq 0$$

• Then,  $\widehat{F_c}$  is uniquely defined as following

$$\widehat{\mathbf{F}_{c}} = -\mathbf{A}_{c}^{t} \, \mathcal{L}_{c}^{-1} \left( \mathbf{D}_{c} \, \mathbf{P}_{c} \, \mathbf{M}_{c}^{-1} \, \Phi_{c} + \mathbf{B}_{c} \right)$$

- The only terms depending on the time are  $\Phi_c$  and  $B_c$
- Equivalently, the polynomial solution governing equation is given by

$$\frac{\mathrm{d}\,\mathsf{U}_c}{\mathrm{d}t} = -\mathsf{P}_c^{-1}\,\mathsf{D}_c^{-1}\left(\mathsf{A}_c\,\widehat{\mathsf{F}_c} + \mathsf{B}_c\right)$$

# remark

• This unique solution does exit since

$$\left( \textit{D}_{c} \textit{P}_{c} \textit{M}_{c}^{-1} \Phi_{c} + \mathsf{B}_{c} 
ight)$$
 .  $\mathbf{1} = 0$ 

#### Different cell subdivisions



Figure: Examples of easily generalizable subdivisions for a triangle cell

# DG is DG

- Only the functional space matters
- The cell subdivision has no influence on the resulting scheme
- Even in the case where  $N_s > N_k$

**TD3** 

# Rotation of a composite signal after one full rotation



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# Rotation of a composite signal after one full rotation



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# Blending low and high order fluxes

• Each face  $f_{mp}^c$  of each subcell  $S_m^c$  will be assigned two fluxes

$$\widetilde{F_{mp}} = \mathcal{F}_{mp}^{FV} + \underbrace{\theta_{mp}}_{\in [0,1]} \underbrace{\left(\widehat{F_{mp}} - \mathcal{F}_{mp}^{FV}\right)}_{\Delta F_{mp}}$$



• 
$$\mathcal{F}_{mp}^{\scriptscriptstyle \mathsf{FV}} := \mathcal{F}\left(\overline{u}_m^c, \overline{u}_p^v, \boldsymbol{n}_{mp}\right)$$
  
•  $\widehat{F_{mp}}$ 

first-order subcell numerical flux

high-order DG reconstructed flux

• The local subcell monolithic DG/FV then writes as follows

$$\frac{\mathrm{d}\,\overline{u}_{m}^{c}}{\mathrm{d}t} = -\frac{1}{|S_{m}^{c}|} \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} I_{mp} \widetilde{F_{mp}}$$

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## Numerical flux

$$\mathcal{F}(u^-, u^+, n) = rac{\left( F(u^-) + F(u^+) 
ight)}{2} \cdot n - rac{\gamma(u^-, u^+, n)}{2} \left( u^+ - u^- 
ight)$$

• 
$$\gamma(u^-, u^+, \boldsymbol{n}) \geq \max_{\boldsymbol{w} \in I(u^-, u^+)} \left( |\boldsymbol{F}'(\boldsymbol{w}) \boldsymbol{.} \boldsymbol{n}| \right)$$

• 
$$I(a, b) = [min(a, b), max(a, b)]$$

In the system case, we make use of either Rusanov, HLL, HLL-C, ...

## Time integration

- For sake of simplicity, we focus on forward Euler (FE) time stepping, as SSP Runge-Kutta can be formulated as convex combinations of FE
- The semi-discrete scheme provided with FE time integration writes

$$\overline{u}_{m}^{c,n+1} = \overline{u}_{m}^{c,n} - \frac{\Delta t}{|S_{m}^{c}|} \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} I_{mp} \widetilde{F_{mp}}$$

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# Reformulation of the monolithic subcell scheme

• 
$$\gamma_{mp} := \gamma \left( \overline{u}_{m}^{c,n}, \overline{u}_{p}^{v,n}, \mathbf{n}_{mp} \right)$$
 1st-order FV dissipation coefficient  
•  $\overline{u}_{m}^{c,n+1} = \overline{u}_{m}^{c,n} - \frac{\Delta t}{|S_{m}^{c}|} \left( \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} l_{mp} \widetilde{F_{mp}} \pm \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} l_{mp} \gamma_{mp} \overline{u}_{m}^{c,n} + \mathbf{F}(\overline{u}_{m}^{c,n}) \cdot \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} n_{mp} \right)$   

$$= \left( 1 - \frac{\Delta t}{|S_{m}^{c}|} \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} l_{mp} \gamma_{mp} \right) \overline{u}_{m}^{c,n}$$

$$+ \frac{\Delta t}{|S_{m}^{c}|} \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} l_{mp} \gamma_{mp} \left( \overline{u}_{m}^{c,n} - \frac{\widetilde{F_{mp}} - \mathbf{F}(\overline{u}_{m}^{c,n}) \cdot \mathbf{n}_{mp}}{\gamma_{mp}} \right)$$
  
•  $\overline{u}_{m}^{c,n+1} = \left( 1 - \frac{\Delta t}{|S_{m}^{c}|} \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} l_{mp} \gamma_{mp} \right) \overline{u}_{m}^{c,n} + \frac{\Delta t}{|S_{m}^{c}|} \sum_{S_{p}^{v} \in \mathcal{V}_{m}^{c}} l_{mp} \gamma_{mp} \overline{u_{mp}}^{-}$   
• **Convex combination under CFL condition**

#### Blended Riemann intermediate states



(a) 1st-order situation

(b) Blended flux situation

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# Admissible solution

• G a convex admissible set where the solution has to remain in

• 
$$G = \left\{ u_0 \in [\alpha, \beta] \implies u \in [\alpha, \beta] \right\}$$

• 
$$G = \left\{ u = \begin{pmatrix} \rho \\ \boldsymbol{q} \\ E \end{pmatrix}, \quad \rho > 0, \, p(u) > 0 \right\}$$

• A sufficient condition to ensure  $\overline{u}_m^{c,n+1} \in G$  is that

$$\forall S_{p}^{v} \in \mathcal{V}_{m}^{c}, \qquad \widetilde{u_{mp}}^{\pm} = u_{mp}^{*, \mathsf{FV}} \pm \theta_{mp} \frac{\Delta F_{mp}}{\gamma_{mp}} \in G$$

- We want to prevent to code from crashing (apparition of NaN, ...)
- We want to prevent the apparition of spurious oscillations
- We want to ensure discrete entropy inequalities (?)
- We apply a local blending coefficients smoothening to avoid too stiff transition from high to low orders

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# Find the correct $\theta_{mp}$

SCI

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# **Questions regarding entropy**

• Can we find the  $\theta_{mp}$  coefficients ensuring an entropy inequality?

#### What do we mean by entropy inequality?

- for one or any entropy?
- at the discrete or semi-discrete time level?
- at the cells or subcells space level?

#### If we manage to ensure an entropy inequality, is it worth the effort?

- in terms of accuracy
- in terms of other critical properties to ensure, as positivity for instance

# • Do we really need an entropy inequality to practically capture the entropic weak solution?

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# Definitions

- (η, φ)
- $v(u) = \eta'(u)$
- $\psi(u) = v(u) \boldsymbol{F}(u) \phi(u)$

entropy - entropy flux entropy variable entropy potential flux

for all  $(\eta, \phi)$ 

# Subcell entropy stability at the discrete level

• if 
$$\Delta F_{mp}$$
.  $\left(\overline{u}_{p}^{v,n}-\overline{u}_{m}^{c,n}\right)>0$ ,

$$heta_{mp} \leq \min\left(1, \, rac{\left(\gamma_{mp} - \gamma_{max}
ight)\left(\overline{u}_{p}^{v,n} - \overline{u}_{m}^{c,n}
ight)}{2\,\Delta F_{mp}}
ight)$$

• 
$$\gamma_{\max}$$
 :=  $\max_{w \in I(\overline{u}_m^{c,n}, \overline{u}_p^{v,n})} \left( |\boldsymbol{F}'(w) \cdot \boldsymbol{n}_{mp}| \right)$ 

 $\Rightarrow$  1st order scheme!

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Semi-discrete subcell entropy dissipation

for a given  $(\eta, \phi)$ 

• if 
$$\Delta F_{mp} \cdot \left( v(\overline{u}_{p}^{v,n}) - v(\overline{u}_{m}^{c,n}) \right) > 0$$
,



2nd order scheme!

A. RUEDA-RAMÍREZ, B. BOLM, D. KUZMIN AND G. GASSNER, Monolithic Convex Limiting for Legendre-Gauss-Lobatto Discontinuous Galerkin Spectral Element Methods. Commun. Appl. Math. Comput., 2024.

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# Sub-resolution basis functions

• Let  $\{\varphi_m^c\}_m$  be the sub-resolution basis function such that,  $\forall \psi \in \mathbb{P}^k(\omega_c)$ 

$$\int_{\omega_c} \varphi_m \psi \, \mathrm{d} V = \int_{\mathcal{S}_m^c} \psi \, \mathrm{d} V$$

• Then, given  $v_h^c \in \mathbb{P}^k(\omega_c)$ , it writes

$$\boldsymbol{v}_h^c = \sum_{m=1}^{N_k} \underline{\boldsymbol{v}}_m^c \, \boldsymbol{\varphi}_m^c$$

# Semi-discrete cell entropy dissipation

# for a given $(\eta, \phi)$

 $N_{\rm s} = N_k$ 

• 
$$\Delta \eta_c := \frac{\mathrm{d}}{\mathrm{d}t} \oint_{\omega_c} \eta(u_h^c) \,\mathrm{d}V = \oint_{\omega_c} v(u_h^c) \,\partial_t u_h^c \,\mathrm{d}V = \int_{\omega_c} v_h^c \,\partial_t u_h^c \,\mathrm{d}V$$

• 
$$v_h^c = \sum_{m=1}^{N_k} \underline{v}_m^c \varphi_m^c$$
  $L^2$  projection of  $v(u_h^c)$  onto  $\mathbb{P}^k$ 

• 
$$\Delta \eta_c = \sum_{m=1}^{N_k} \underline{v}_m^c \int_{\omega_c} \varphi_m^c \partial_t u_h^c \, \mathrm{d}V = \sum_{m=1}^{N_k} |S_m^c| \, \underline{v}_m^c \, \frac{\mathrm{d}\overline{u}_m^c}{\mathrm{d}t} = -\sum_{m=1}^{N_k} \underline{v}_m^c \sum_{S_p^\nu \in \mathcal{V}_m^c} I_{mp} \, \widetilde{F_{mp}}$$

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#### Continuous Knapsack problem

• The sufficient condition rewrites as

$$\mathbf{C}_{c}$$
 .  $\mathbf{\Theta}_{c} \leq \mathsf{D}_{c}$ 

•  $\Theta$  contains all the subcells' faces,  $\mathbf{C}_c$  the vector defined as

$$C_{mp}^{c} = \begin{cases} \oint_{f_{mp}} \left( \left( v(u_{h}^{c}) - \underline{v}_{m}^{c} \right) \mathcal{F}_{n} - \left( \psi(u_{h}^{c}) - \psi(u(\underline{v}_{m}^{c})) \right) \cdot \boldsymbol{n}_{mp} \right) dS, & \forall f_{mp} \subset \partial \omega_{c} \\ I_{mp} \left( \underline{v}_{p}^{c} - \underline{v}_{m}^{c} \right) \Delta F_{mp}, & \text{otherwise} \end{cases}$$

$$\bullet D_{c} = \sum_{f_{mp} \in \hat{f}_{c}} I_{mp} \psi(u(\underline{v}_{m}^{c})) \cdot \boldsymbol{n}_{mp} - \sum_{f_{mp} \in \tilde{f}_{c}} I_{mp} \left( \underline{v}_{p}^{c} - \underline{v}_{m}^{c} \right) \mathcal{F}_{mp}^{\mathsf{FV}}$$

$$\bullet \mathcal{F}_{mp}^{\mathsf{FV}} = \mathcal{F} \left( u(\underline{v}_{m}^{c}), u(\underline{v}_{p}^{v}), \boldsymbol{n}_{mp} \right) & \text{modified FV numerical flux}$$

$$\bullet \underline{\mathsf{Because}} \quad D_{c} \geq 0 \quad \text{the Knapsack problem is indeed solvable}$$

**Y. LIN** AND **J. CHAN**, *High order entropy stable discontinuous Galerkin spectral element methods through subcell limiting.* JCP, 2024.

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# Greedy algorithm

• Find  $\mathbf{0} \leq \mathbf{\Theta} \leq \mathbf{\Theta}^{e} \leq \mathbf{1}$  maximizing  $\sum \theta_{mp}$  such that

$$\mathbf{C}_{c}$$
 .  $\mathbf{\Theta}_{c} \leq \mathsf{D}_{c}$ 

•  $\theta_{mp}^{e}$  being any given supplementary constraint

# High-order accuracy preservation

- Substituting *u<sub>h</sub>* by a smooth solution *u*
- $h_c$  is the diameter of cell  $\omega_c$
- Then, we have that

$$\mathbf{C}_{c}$$
. 1 – D<sub>c</sub> =  $|\omega_{c}| \mathcal{O}(h_{c}^{k+1})$ 

• This finally implies that

$$\widetilde{F_{mp}} = \widehat{F_{mp}} + (\theta_{mp} - 1) \Delta F_{mp} = \widehat{F_{mp}} + \mathcal{O}(h_c^{k+2})$$

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Entropy stabilities

Numerical results

## Linear advection of a composite signal



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Entropy stabilities

Numerical results



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Entropy stabilities Numerical results

#### Non-linear non-convex flux Buckley case



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80 cells

Entropy stabilities

Numerical results

#### Non-linear non-convex flux Buckley case



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80 cells

#### KPP non-convex flux problem

 $\eta(\mathbf{U}) = \frac{1}{2}\mathbf{U}^2$ 



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Figure:  $\mathbb{P}^5$  pure DG with positivity limiter and  $\mathbb{P}^5$ -DG/FV monolithic scheme with cell entropy stability on 20 cells

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Conclusion of entropy?

# Questions regarding entropy $\longrightarrow$ pieces of answer

• Can we find  $\theta_{mp}$  coefficients ensuring an entropy inequality?

 $\hookrightarrow$  Yes!

- What do we mean by entropy inequality, and is it worth the effort?
  - for any entropy, at the discrete time level and for any subcell

 $\hookrightarrow$  1<sup>st</sup>-order

for a given entropy, at the semi-discrete time level for any subcells

 $\hookrightarrow$  2<sup>nd</sup>-order

for a given entropy, at the semi-discrete time level for any cells

 $(k+1)^{\text{th}}$ -order  $\hookrightarrow \mathcal{F}_{mp}^{\text{FV}} = \mathcal{F}\left(\boldsymbol{u}(\underline{\boldsymbol{v}}_{m}^{c}), \, \boldsymbol{u}(\underline{\boldsymbol{v}}_{p}^{v}), \, \boldsymbol{n}_{mp}\right)$ 

Do we absolutely need entropy stability while aiming for high order?

 $\hookrightarrow$  Unclear...  $\Rightarrow$  GMP and LMP + relaxation

#### Introduction

- 2 DG as a subcell FV
- 3 Monolithic subcell DG/FV scheme
- 4 Entropy stabilities
- 5 Maximum principles
  - 6 Conclusion

# Global maximum principle

$$\theta_{\textit{mp}} \leq \min\left(1, \left|\frac{\gamma_{\textit{mp}}}{\Delta F_{\textit{mp}}}\right| \min\left(\beta - u_{\textit{mp}}^{*, \mathsf{FV}}, u_{\textit{mp}}^{*, \mathsf{FV}} - \alpha\right)\right)$$



• 
$$\alpha_m^c := \min_{S_q^w \in \mathcal{N}(S_m^c)} \left(\overline{u}_q^{w,n}\right)$$

$$eta_m^{m{c}} := \max_{\substack{S_a^{m{w}} \in \mathcal{N}(S_m^{m{c}})}} ig(\overline{m{L}}$$

 $\overline{u}^{c,n+1}$ 

w,n

$$\theta_{mp} \leq \min\left(1, \left|\frac{\gamma_{mp}}{\Delta F_{mp}}\right| \left\{ \begin{array}{ll} \min\left(\beta_{p}^{\nu} - u_{mp}^{*, \mathsf{FV}}, u_{mp}^{*, \mathsf{FV}} - \alpha_{m}^{\mathsf{c}}\right) & \quad \text{if } \Delta F_{mp} > 0\\ \min\left(\beta_{m}^{c} - u_{mp}^{*, \mathsf{FV}}, u_{mp}^{*, \mathsf{FV}} - \alpha_{p}^{\nu}\right) & \quad \text{if } \Delta F_{mp} < 0 \end{array} \right)$$

and

- The wider set  $\mathcal{N}(S_m^c)$  is, the softer this local maximum principle will be
- Smooth extrema relaxation to preserve accuracy

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Local subcell monolithic DG/FV scheme

 $\in [\alpha, \beta]$ 

 $\in [\alpha_m^c, \beta_m^c]$ 

## Burgers equation

# $u_0(x,y) = \sin(2\pi (x+y))$

(a) Solution submean values

(b) Blending coefficients

Figure: ₽5-DG/FV scheme with GMP and relaxed-LMP on 242 cells

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#### KPP non-convex flux problem



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Positivity of the density and internal energy, at the subcell scale

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Local subcell monolithic DG/FV scheme

# Definitions

• 
$$\widetilde{F}_{mp} := \mathcal{F}_{mp}^{\text{FV}} + \Theta_{mp} \underbrace{\left(\widehat{F}_{mp} - \mathcal{F}_{mp}^{\text{FV}}\right)}_{\Delta F_{mp}}$$
 convex blended flux  
•  $\Theta_{mp} = \begin{pmatrix} \theta_{mp}^{\rho} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \theta_{mp}^{q} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \theta_{mp}^{E} \end{pmatrix}$   
•  $\mathcal{F}_{mp}^{\text{FV}} := \mathcal{F}\left(\overline{V}_{m}^{c,n}, \overline{V}_{p}^{v,n}, \mathbf{n}_{mp}\right)$  Global L-F, Rusanov, HLL(C), ...

• 
$$\theta_{mp}^{\rho} = \theta_{mp}^{(1)} \theta_{mp}^{(2)}$$

$$heta_{\textit{mp}}^{(1)} \leq \min\left(1, \left|rac{\gamma_{\textit{mp}}}{\Delta F_{\textit{mp}}^{
ho}}\right| 
ho_{\textit{mp}}^{*, \, {\scriptscriptstyle {\rm FV}}}
ight)$$

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# Positivity of the internal energy

• 
$$A_{mp} = \frac{1}{(\gamma_{mp})^2} \left( \frac{1}{2} \left\| \Delta F^{\boldsymbol{q}}_{mp} \right\|^2 - \theta^{(1)}_{mp} \Delta F^{\rho}_{mp} \Delta F^{\boldsymbol{E}}_{mp} \right)$$
  
•  $B_{mp} = \frac{1}{\gamma_{mp}} \left( \boldsymbol{q}^{*,FV}_{mp} \cdot \Delta F^{\boldsymbol{q}}_{mp} - \rho^{*,FV}_{mp} \Delta F^{\boldsymbol{E}}_{mp} - \theta^{(1)}_{mp} E^{*,FV}_{mp} \Delta F^{\rho}_{mp} \right)$ 

•  $M_{mp} = \rho_{mp}^{*, FV} E_{mp}^{*, FV} - \frac{1}{2} \left\| \boldsymbol{q}_{mp}^{*, FV} \right\|^2$ 

$$heta_{mp}^{(2)} \leq \min\left(1, \; rac{M_{mp}}{\left|B_{mp}\right| + \max\left(0, A_{mp}
ight)}
ight)$$

• 
$$\theta_{mp}^{\rho} = \theta_{mp}^{\rho(1)} \theta_{mp}^{(2)}, \quad \theta_{mp}^{q^{x}} = \theta_{mp}^{(2)}, \quad \theta_{mp}^{q^{y}} = \theta_{mp}^{(2)}, \quad \theta_{mp}^{E} = \theta_{mp}^{(2)}$$

A. RUEDA-RAMÍREZ, B. BOLM, D. KUZMIN AND G. GASSNER, Monolithic Convex Limiting for Legendre-Gauss-Lobatto Discontinuous Galerkin Spectral Element Methods. Commun. Appl. Math. Comput., 2024.

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# LMP

$$\overline{V}_m^{c,n+1} \in [\alpha_m^c, \beta_m^c]$$

• 
$$\mathbf{v} \in \left\{ \rho, \, \mathbf{q}^{\mathbf{x}}, \, \mathbf{q}^{\mathbf{y}}, \, \mathbf{E} \right\}$$

• 
$$\alpha_m^c := \min_{S_q^w \in \mathcal{N}(S_m^c)} \left( \overline{v}_q^{w,n}, v_{mq}^{*, \mathrm{FV}} \right)$$
 and  $\beta_m^c := \max_{S_q^w \in \mathcal{N}(S_m^c)} \left( \overline{u}_q^{w,n}, v_{mq}^{*, \mathrm{FV}} \right)$ 

$$\theta_{mp} \leq \min\left(1, \left|\frac{\gamma_{mp}}{\Delta F_{mp}}\right| \left\{ \begin{array}{l} \min\left(\beta_p^{v} - u_{mp}^{*, Fv}, u_{mp}^{*, Fv} - \alpha_m^{c}\right) & \text{if } \Delta F_{mp} > 0\\ \min\left(\beta_m^{c} - u_{mp}^{*, Fv}, u_{mp}^{*, Fv} - \alpha_p^{v}\right) & \text{if } \Delta F_{mp} < 0 \end{array} \right)$$

#### Smooth extrema relaxation to preserve accuracy

# Sod shock tube test case



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Local subcell monolithic DG/FV scheme

10 cells

#### Smooth isentropic solution

# $ho_0 = 1 + 0.9999999 \sin(2\pi x)^{-1}$

	exist solution					
	L <sub>1</sub>		L <sub>2</sub>		$\theta_{mp}$	
h	$E_{L_1}^h$	$q_{L_1}^h$	$E_{L_2}^h$	$q_{L_2}^h$	min. $\theta_{mp}$	aver. $\theta_{mp}$
$\frac{1}{10}$	9.07E-4	5.86	1.23È-3	5.90	2.00E-1	0.981
$\frac{1}{20}$	1.56E-5	4.03	2.05E-5	3.83	1.92E-1	0.997
$\frac{1}{40}$	9.53E-7	4.89	1.44E-6	4.85	5.65E-4	0.999
$\frac{1}{80}$	3.21E-8	4.80	5.00E-8	4.87	3.48E-5	0.999
$\frac{1}{160}$	1.15E-9	-	1.71E-9	-	1.00	1.00

Table: Convergence rates of the P<sup>4</sup>-DG/FV scheme with positivity and relaxed-LMP

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#### Sod shock tube problem in cylindrical geometry



Figure: ℙ<sup>5</sup>-DG/FV with positivity and relaxed-LMP on a 110 cells mesh

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(a) Density map

# Sedov point blast problem in cylindrical geometry



#### Mach 3 forward-facing step



Figure: Monolithic subcell DG/FV scheme with positivity and relaxed-LMP

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## Mach 20 hypersonic flow over half cylinder



Figure: Monolithic subcell DG/FV scheme: density and blending coefficients

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Conclusion?

# Monolithic local subcell DG/FV scheme

- Reformulate DG schemes as subgrid FV-like schemes:
  - regardless the type of mesh used
  - regardless the space dimension (*in theory*...)
  - regardless the cell subdivision ( $N_s \ge N_k$ )
- Combine high-order reconstructed fluxes and 1<sup>st</sup>-order FV fluxes
  - ensuring a maximum or positivity preserving principle at the subcell scale
  - ensuring different entropy stability inequalities
  - reducing significantly the apparition of spurious oscillations
  - preserving the very accurate subcell resolution of DG schemes

# Questions

Is an entropy inequality for one entropy enough?



Is entropy inequality absolutely needed?

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Local subcell monolithic DG/FV scheme

Maybe not  $\implies$  GMP + relaxed LMP

# Articles on this topic

- **F.V**, A Posteriori Correction of High-Order DG Scheme through Subcell Finite Volume Formulation and Flux Reconstruction. JCP, 2018.
- A. HAIDAR, F. MARCHE AND F.V, A posteriori Finite-Volume local subcell correction of high-order discontinuous Galerkin schemes for the nonlinear shallow-water equations. JCP, 2022.
- **F.V** AND **R. ABGRALL**, A posteriori local subcell correction of DG schemes through Finite Volume reformulation on unstructured grids. SIAM SISC, 2023.
- A. HAIDAR, F. MARCHE AND F.V, Free-boundary problems for wave-structure interactions in shallow-water: DG-ALE description and local subcell correction. JSC, 2023.
- **A. HAIDAR, F. MARCHE** AND **F.V**, A robust DG-ALE formulation for nonlinear shallow-water interactions with a floating object. JSC, 2024.
- **F.V**, Monolithic local subcell DG/FV convex property preserving scheme on unstructured grids and entropy consideration. JCP, 2024.

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- **F.V**, A Posteriori Correction of High-Order DG Scheme through Subcell Finite Volume Formulation and Flux Reconstruction. JCP, 2018.
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- A. HAIDAR, F. MARCHE AND F.V, Free-boundary problems for wave-structure interactions in shallow-water: DG-ALE description and local subcell correction. JSC, 2023.
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